

What If...? Running Airflow Tasks without the workers





\$ cat weilee.py

```
__name__ = 李唯 / Wei Lee
__what_i_am_doing__ = [
    Software Engineer @ Astronomer,
    Committer @ Apache Airflow,
    First Time Speaker @ Airflow Summit
]
__github__ = Lee-W
__linkedin__ = clleew
__site__ = https://wei-lee.me
```



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\$ python weilee.py

File "weilee.py", line 1
__name__ = 李唯 / Wei Lee

SyntaxError: invalid syntax



QR Code links to this slide deck





```
from __future__ import annotations
     import pendulum
     from airflow import DAG
     from airflow.operators.bash import BashOperator
     with DAG(1
         dag_id="example_dag", ]
         start_date=pendulum.datetime(2021, 1, 1, tz="UTC"), \tag{\sqrt}
         schedule=None,
10
11
         catchup=False, \
12
     ): ₹
13
         bash_task = BashOperator(task_id="bash_task", bash_command="echo example")
```



```
from __future__ import annotations
    import pendulum
    from airflow import DAG
    from airflow.operators.bash import BashOperator
   with DAG(1
       dag_id="example_dag", ]
       start_date=pendulum.datetime(2021, 1, 1, tz="UTC"),
10
       schedule=None,
11
       catchup=False, 3
12
13
```



```
from __future__ import annotations
     import pendulum
     from airflow import DAG
     from airflow.operators.bash import BashOperator
     with DAG(1
         dag_id="example_dag", ]
         start_date=pendulum.datetime(2021, 1, 1, tz="UTC"), \[
         schedule=None,
10
11
         catchup=False, 3
12
13
        bash_task = BashOperator(task_id="bash_task", bash_command="echo example")
```

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Let's start with how a typical task works now



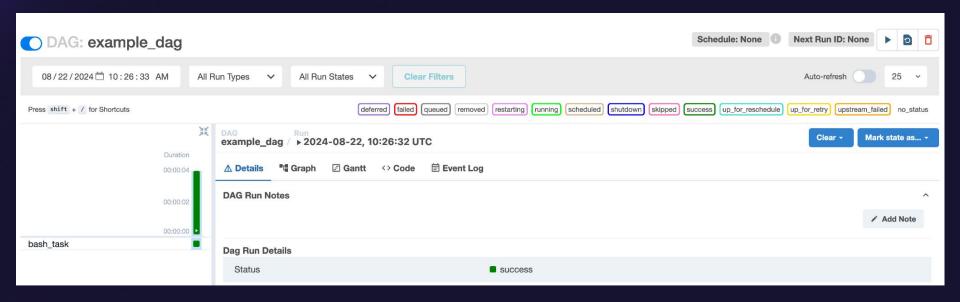


Under the hood, it runs "execute".

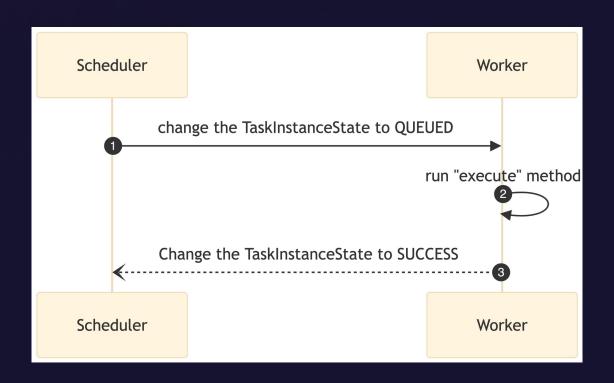
```
class BashOperator(BaseOperator):
 19 >
18
          template_fields: Sequence[str] == ("bash_command", - "env", - "cwd") \[
          template_fields_renderers = {"bash_command": "bash", "env": "json"}
          template_ext: Sequence[str] = (".sh", ".bash")]
          ui_color = "#f0ede4" \[
13
12 >
          def __init__(
 11
 10
          @cached_property
          def subprocess_hook(self):
          @staticmethod \
          def refresh_bash_command(ti: TaskInstance) -> None:
          def get_env(self, context):
          def execute(self, context: Context):
255
          def on_kill(self) -> None:
```













Since Airflow 2.2

deferrable operator was introduced

Deferrable Tasks (AIP-40)

Deferrable tasks allows operators or sensors to defer themselves until a light-weight async check passes, at which point they can resume executing. Most importantly, this results in the worker slot, and most notably any resources used by it, to be returned to Airflow. This allows simple things like monitoring a job in an external system or watching for an event to be much cheaper.

To support this feature, a new component has been added to Airflow, the triggerer, which is the daemon process that runs the asyncio event loop.

Airflow 2.2.0 ships with 2 deferrable sensors, DateTimeSensorAsync and TimeDeltaSensorAsync, both of which are drop-in replacements for the existing corresponding sensor.

More information can be found at:

Deferrable Operators & Triggers



Non-Deferrable Operator

Submit Job to Spark Cluster

Poll Spark Cluster for Job Status

Receive Terminal
Status for Job on
Spark Cluster

Worker Slot Allocated



Non-Deferrable Operator

Submit Job to Spark Cluster

Poll Spark Cluster for Job Status

Status for Job on Spark Cluster

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Non-Deferrable Operator

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Non-Deferrable Operator

Submit Job to Spark Cluster

Poll Spark Cluster for Job Status

Receive Terminal Status for Job on Spark Cluster

Worker Slot Allocated

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But why? → Release worker slots

Deferrable Operator





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But why? → Release worker slots

Deferrable Operator





This page is for deferrable operators.



Release worker slots. And...?

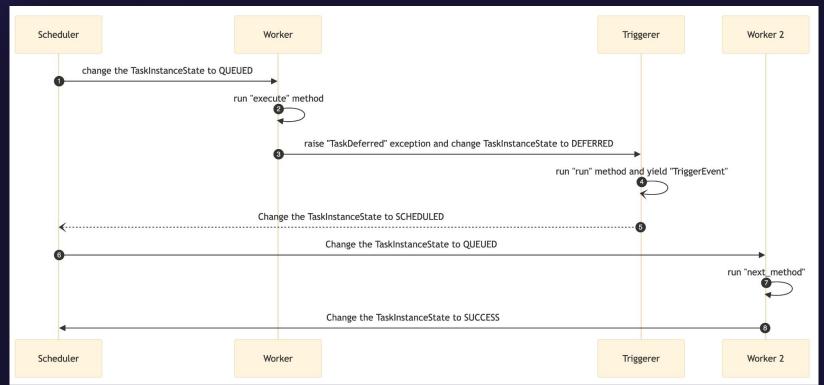
Reduce resource usage







How does deferrable operators work?







How does deferrable operator work?

Well... we still run "execute" first.

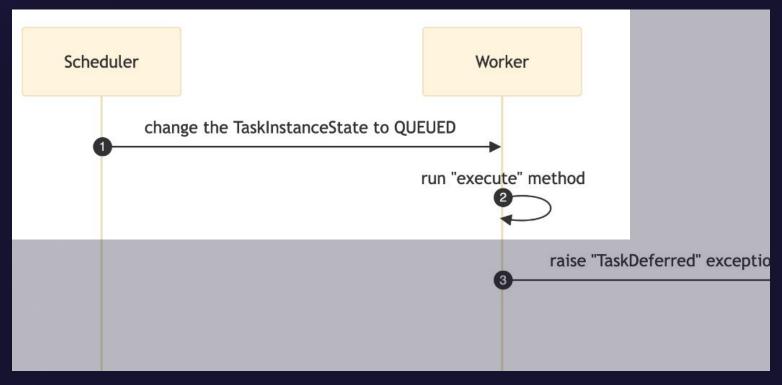
```
class S3KeysUnchangedSensor(BaseSensorOperator):
         def execute(self, context: Context) -> None: 1
             """Airflow runs this method on the worker and defers using the trigger
             if not self.deferrable:
                 super().execute(context)
            else:
       if not self.poke(context):
                     self.defer(
388
                         timeout=timedelta(seconds=self.timeout), 1
                         trigger=S3KeysUnchangedTrigger(
                             bucket_name=self.bucket_name,
                             prefix=self.prefix,
```



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How does deferrable operators work?







How does deferrable operator work?

The main difference is executing "self.defer" and raise a TaskDeferred exception through it

```
class S3KeysUnchangedSensor(BaseSensorOperator):
            super().execute(context)
        else:
            if not self.poke(context):
                self.defer(
                    timeout=timedelta(seconds=self.timeout),
                    trigger=S3KeysUnchangedTrigger(
                        bucket_name=self.bucket_name,
                        prefix=self.prefix,
                        inactivity_period=self.inactivity_period, \[ \]
                        min_objects=self.min_objects,
                        previous_objects=self.previous_objects, \[ \]
                        inactivity_seconds=self.inactivity_seconds,
```



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How does deferrable operator work?

Then, it's the triggerer's turn to run.

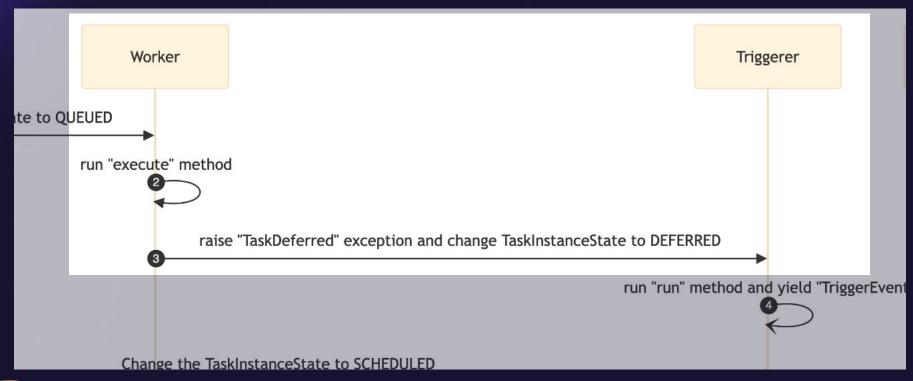
```
class S3KeysUnchangedSensor(BaseSensorOperator):
                  super().execute(context)
                  if not self.poke(context): 
                      self.defer(
388
                          timeout=timedelta(seconds=self.timeout),
                          trigger=S3KeysUnchangedTrigger(
  3
                              bucket_name=self.bucket_name,
                              prefix=self.prefix,
                              inactivity_period=self.inactivity_period, \[ \]
                              min_objects=self.min_objects,
                              previous_objects=self.previous_objects, \[ \]
                               inactivity_seconds=self.inactivity_seconds,
```



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How does deferrable operators work?







How does deferrable operator work?

Execute the async "run" method in the triggerer

```
async def run(self) -> AsyncIterator[TriggerEvent]:
194
```





How does deferrable operator work?

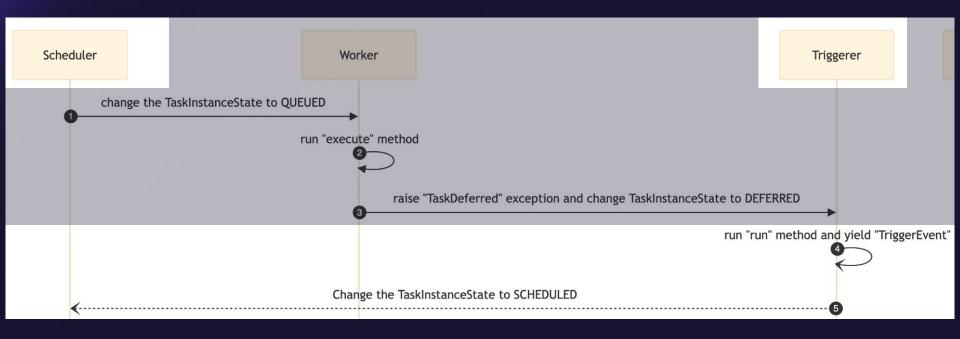
yield a TriggerEvent when it finished

```
194
                              yield TriggerEvent(result)
```





How does deferrable operators work?







How does deferrable operator work?

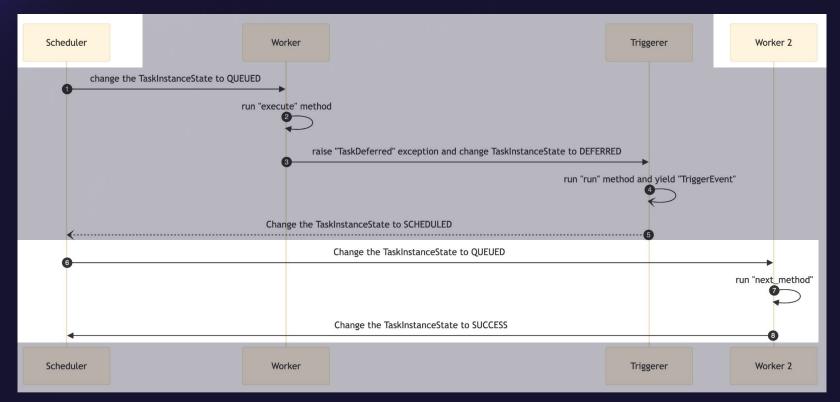
Execute the "execute_complete" method in another worker

```
def execute_complete(self, context: Context, event: dict[str, Any] | None = None) -> None:
             Execute when the trigger fires - returns immediately.
             Relies on trigger to throw an exception, otherwise it assumes execution was successful.
             event = validate_execute_complete_event(event)
             if event and event["status"] == "error":]
                 raise AirflowException(event["message"])
              return None
407
```





How does deferrable operators work?







Do we really need to run it in the worker first?

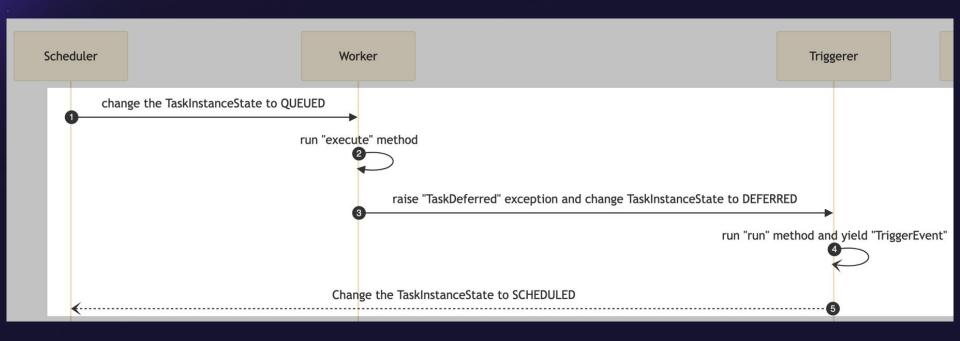
the only logic before deferring







What can we do?

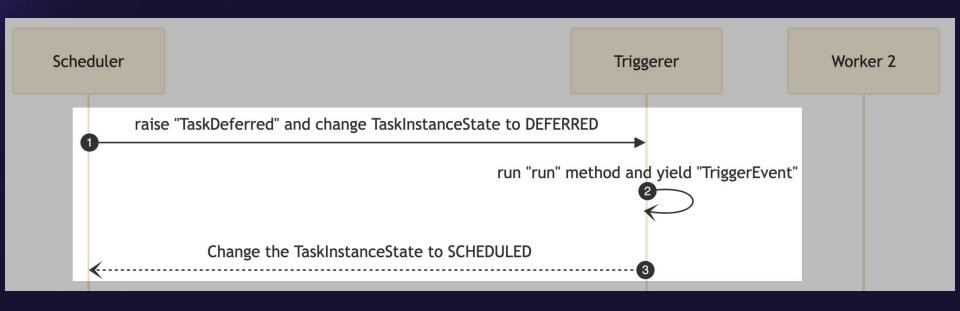






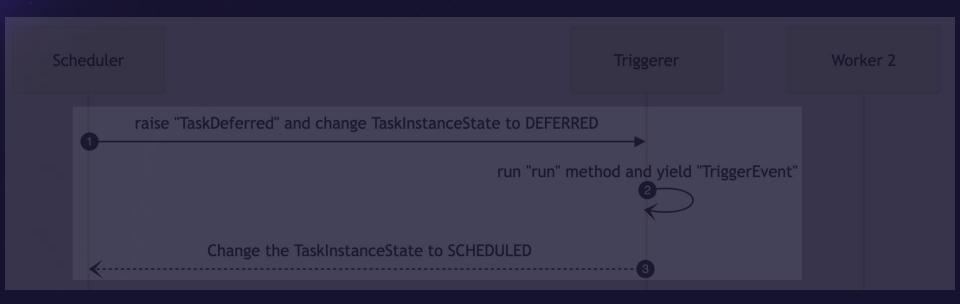
What can we do?

Start task execution in the triggerer



What can we do?

Start task execution in the triggerer





This page is for new features.



Start task execution in the worker

```
from datetime import timedelta
    from typing import Any
    from airflow.sensors.base import BaseSensorOperator
     from airflow.triggers.temporal import TimeDeltaTrigger
     from airflow.utils.context import Context
    class WaitOneHourSensor(BaseSensorOperator): 1
        def execute(self, context: Context) -> None:
     self.defer(
10
     trigger=TimeDeltaTrigger(timedelta(hours=1)), method_name="execute_complete";
12
13
14
        def execute_complete()
15
            self, context: Context, event: dict[str, Any] | None = None
     ) -> None: ↓
     ····· # We have no more work to do here. Mark as complete. J
17
18
     return]
```





```
class WaitHoursSensor(BaseSensorOperator): ]
         start_trigger_args = StartTriggerArgs()
17
             trigger_cls="airflow.triggers.temporal.TimeDeltaTrigger", ]
             trigger_kwargs={"delta": timedelta(hours=1)},
      next_method="execute_complete", \tag{\tau}
13
      next_kwargs=None,
             timeout=None, \1
11
      · · · ) ]
         def __init__(
             self,
             *args: list[Any],
             trigger_kwargs: dict[str, Any] | None, \
      start_from_trigger: bool, \[ \]
             **kwargs: dict[str, Any],:
         ) -> None: \( \)
             super().__init__(*args, **kwargs);
             self.start_trigger_args.trigger_kwargs = trigger_kwargs
26
             self.start_from_trigger = start_from_trigger
         def execute_complete(]
             self, context: Context, event: dict[str, Any] | None = None
         ) -> None: ₹
             # We have no more work to do here. Mark as complete.
             return
```



StartTriggerArgs and start_from_trigger

```
self.start_from_trigger = start_from_trigger
```



StartTriggerArgs and start from trigger

```
start_trigger_args = StartTriggerArgs()
trigger_cls="airflow.triggers.temporal.TimeDeltaTrigger",
trigger_kwargs={"delta": timedelta(hours=1)},
next_method="execute_complete",
next_kwargs=None,
timeout=None,
```



StartTriggerArgs vs self.defer



```
class WaitHoursSensor(BaseSensorOperator): ]
         start_trigger_args = StartTriggerArgs(
             trigger_cls="airflow.triggers.temporal.TimeDeltaTrigger", \
             trigger_kwargs={"delta": timedelta(hours=1)},
             next_method="execute_complete", ]
             next_kwargs=None, ]
             timeout=None, 1
         def __init__(
             *args: list[Any],
             trigger_kwargs: dict[str, Any] | None,
             start_from_trigger: bool, \( \)
             **kwarqs: dict[str, Any], ]
         ) -> None: ]
             super().__init__(*args, **kwargs)
             self.start_trigger_args.trigger_kwargs = trigger_kwargs
26
             self.start_from_trigger = start_from_trigger
         def execute_complete(
             self, context: Context, event: dict[str, Any] | None = None
         ) -> None: ]
             # We have no more work to do here. Mark as complete.
```

```
from datetime import timedelta
from typing import Any
from airflow.sensors.base import BaseSensorOperator
from airflow.triggers.temporal import TimeDeltaTrigger
from airflow.utils.context import Context
class WaitOneHourSensor(BaseSensorOperator):
    def execute(self, context: Context) -> None:
        self.defer(]
            trigger=TimeDeltaTrigger(timedelta(hours=1)),
           method_name="execute_complete";
    def execute_complete(
        self, context: Context, event: dict[str, Any] | None = None
    ) -> None: ]
        # We have no more work to do here. Mark as complete. -
```



StartTriggerArgs vs self.defer

```
start_trigger_args = StartTriggerArgs(
    trigger_cls="airflow.triggers.temporal.TimeDeltaTrigger",
   next_method="execute_complete", ]
next_kwargs=None, 
   timeout=None, \
) 1
   def execute(self, context: Context) -> None: ]
       self.defer(]
   trigger=TimeDeltaTrigger(timedelta(hours=1)), 
   method_name="execute_complete";
   · · · · · ) ]
```





trigger_cls

```
start_trigger_args = StartTriggerArgs(]
trigger_cls="airflow.triggers.temporal.TimeDeltaTrigger",
trigger_kwargs={"delta": timedelta(hours=1)},
trigger_kwargs={"delta": timedelta(hours=1)},
trigger_kwargs=Nod="execute_complete",
trigger_kwargs=Nod="execute_complete",
trigger_kwargs=Node,
trigger_k
```





trigger_kwargs

```
timeout=None,
     trigger=TimeDeltaTrigger(timedelta(hours=1)),
     method_name="execute_complete"
```





next_method

```
start_trigger_args = StartTriggerArgs(\]
trigger_cls="airflow.triggers.temporal.TimeDeltaTrigger",\]
trigger_kwargs={"delta": timedelta(hours=1)},\]
next_method="execute_complete",\]
next_kwargs=None,\]
timeout=None,\]
```



```
rdef execute(self, context: Context) -> None: 1
rv: self.defer(1
rv: self.defer(1
rv: trigger=TimeDeltaTrigger(timedelta(hours=1)), 1
rv: method_name="execute_complete";
rv: limedeltaTrigger(timedelta(hours=1)), 1
rv: method_name="execute_complete";
```



args with default values





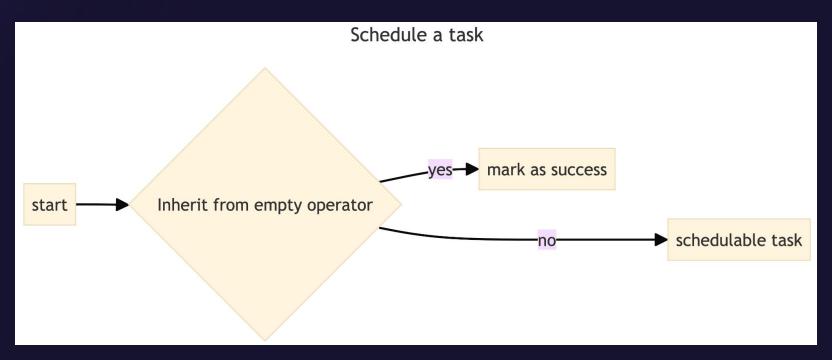
Under the hood

```
def schedule_tis(
              schedulable_tis: Iterable[TI],
              for ti in schedulable_tis:
                  if TYPE_CHECKING:
                      assert ti.taskī
                  if (1
                      ti.task.inherits_from_empty_operator
                      and not ti.task.on_execute_callback
                      and not ti.task.on_success_callback
                      and not ti.task.outlets
                      dummy_ti_ids.append((ti.task_id, ti.map_index));
                  # check "start_trigger_args" to see whether the operator supports start execution from triggerer.
                  # if so, we'll then check "start_from_trigger" to see whether this feature is turned on and defera
                  # this task.
                  elif ti.task.start_trigger_args is not None:
                      context = ti.get_template_context()
                      start_from_trigger = ti.task.expand_start_from_trigger(context=context, session=session)
                       if start_from_trigger:
1588
                          ti.start date = timezone.utcnow()
                          if ti.state != TaskInstanceState.UP_FOR_RESCHEDULE:
                               ti.try_number += 17
                           ti.defer_task(exception=None, session=session)
                       else:
                          schedulable_ti_ids.append((ti.task_id, ti.map_index));
                  else:
                      schedulable_ti_ids.append((ti.task_id, ti.map_index))
```

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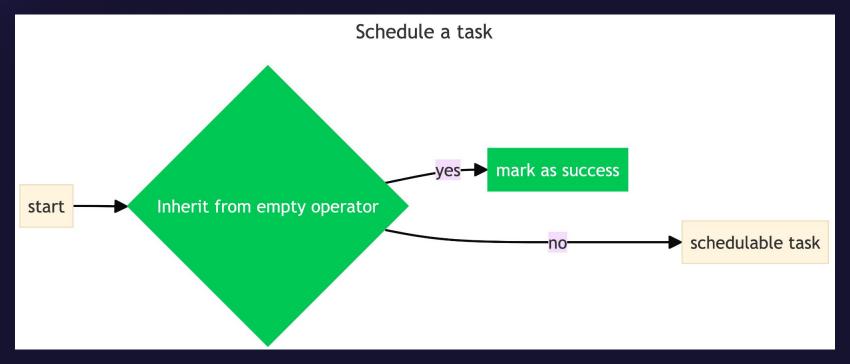
Under the hood (it used to be...)







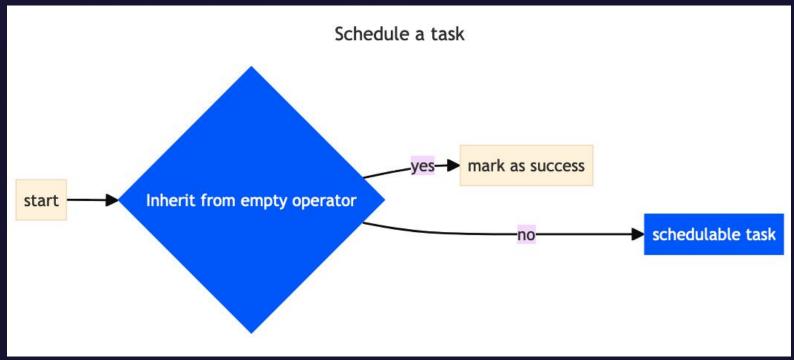
Under the hood (it used to be...)





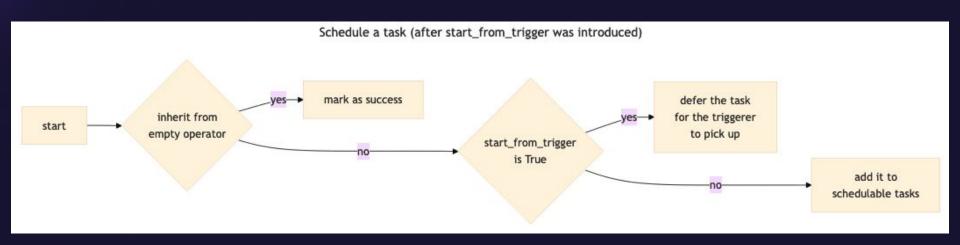


Under the hood (it used to be...)

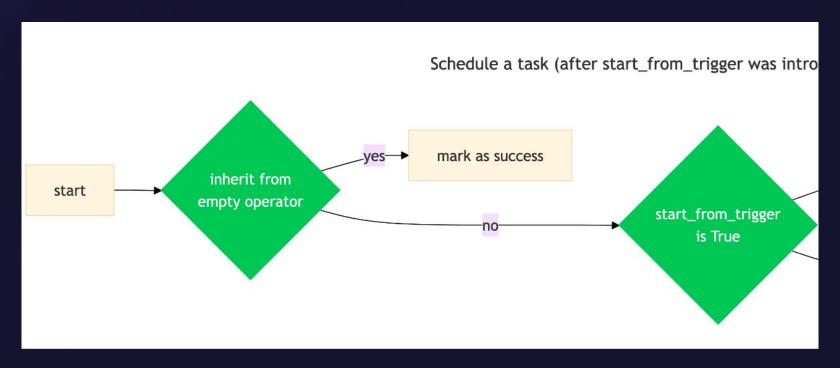




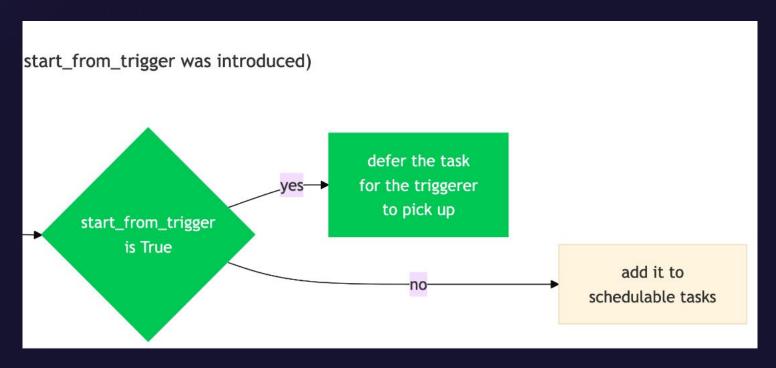




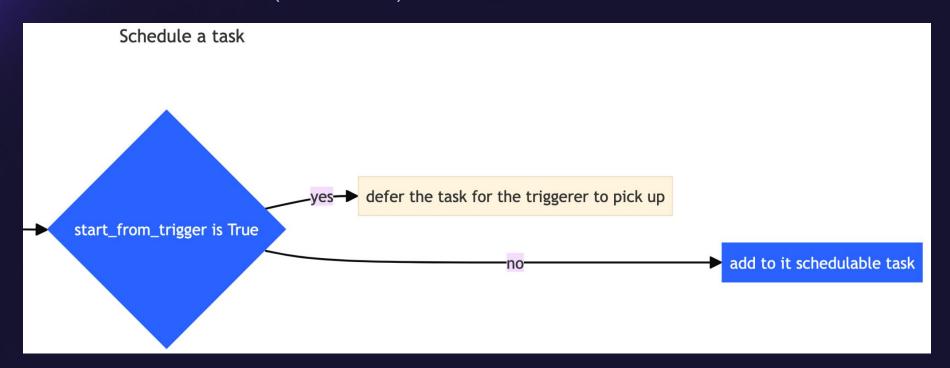




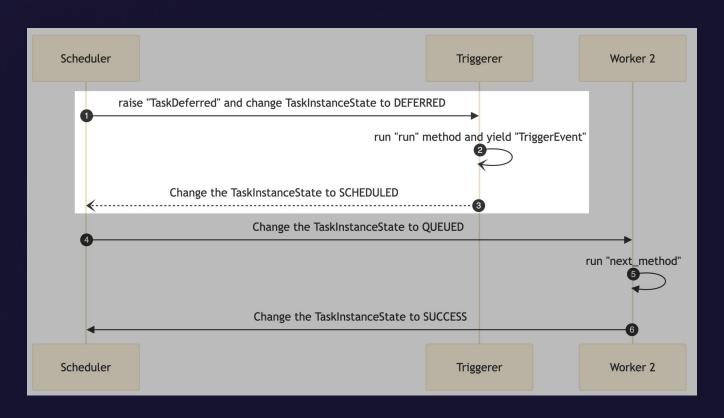
















We don't even have a next method to run after trigger finish its execution?



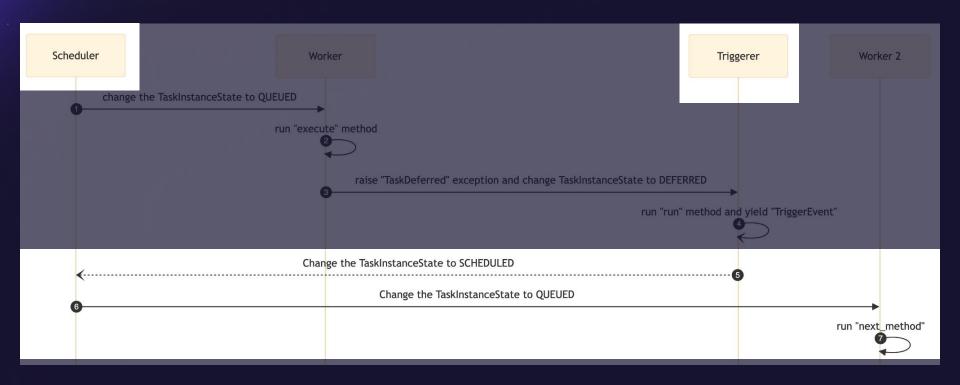
Especially when "next_method" does nothing

```
from datetime import timedelta
     from typing import Any
     from airflow.sensors.base import BaseSensorOperator
     from airflow.triggers.temporal import TimeDeltaTrigger
     from airflow.utils.context import Context
     class WaitOneHourSensor(BaseSensorOperator):
         def execute(self, context: Context) -> None:
             self.defer(]
                 trigger=TimeDeltaTrigger(timedelta(hours=1)), method_name="execute_complete"
14
         def execute_complete(
15
             self, context: Context, event: dict[str, Any] | None = None
         ) -> None: 1
16
             # We have no more work to do here. Mark as complete. I
18
             return1
```





What can we do?

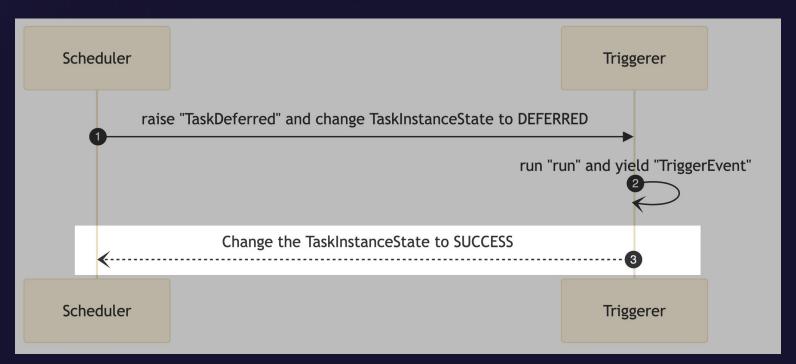






What're the things we want to change?

End task execution in the triggerer





End task execution in the worker

```
from datetime import timedelta
     from typing import Anyl
     from airflow.sensors.base import BaseSensorOperator
     from airflow.triggers.temporal import TimeDeltaTrigger
     from airflow.utils.context import Context
     class WaitOneHourSensor(BaseSensorOperator): \[ \]
        def execute(self, context: Context) -> None:
     self.defer()
10
     trigger=TimeDeltaTrigger(timedelta(hours=1)), method_name="execute_complete"
11
     . . . . . . . . ) 7
12
13
14
        def execute_complete()
15
             self, context: Context, event: dict[str, Any] | None = None
16
         ) -> None: 1
     ·····# We have no more work to do here. Mark as complete. 🕽
     return]
18
```





End task execution in the worker

```
from datetime import timedelta
    from typing import Anyl
    from airflow.sensors.base import BaseSensorOperator
    from airflow.triggers.temporal import TimeDeltaTrigger
    from airflow.utils.context import Context
    class WaitOneHourSensor(BaseSensorOperator): \[ \]
       def execute(self, context: Context) -> None: ]
    self.defer(
10
    11
12
    ] (
13
14
       def execute_complete(
15
           self, context: Context, event: dict[str, Any] | None = None
16
       ) -> None: 1
    ····· # We have no more work to do here. Mark as complete. 🕽
18
    return]
```





Well... we need to make some change in the trigger this time

```
class TimeDeltaTrigger(DateTimeTrigger):
          def __init__(
  8
                 self,
                  delta: datetime.timedelta,
  6
                  end_from_trigger: bool = False
              ) -> None: ₹
  3
              super().__init__()
                  moment=timezone.utcnow() + delta,
                  end_from_trigger=end_from_trigger
113
```

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Well... we need to make some change in the trigger

```
class DateTimeTrigger(BaseTrigger):
         async def run(self) -> AsyncIterator[TriggerEvent]:
             for step in 3600, 60, 10:
                seconds_remaining = (
                         self.moment - pendulum.instance(timezone.utcnow())
14
                 while seconds_remaining > 2 * step:
                     self.log.info("%d seconds remaining; sleeping %s seconds", seconds_remaining, step)
                     await asyncio.sleep(step)
                     seconds_remaining = (
                             self.moment - pendulum.instance(timezone.utcnow())
            while self.moment > pendulum.instance(timezone.utcnow()):
                 await asyncio.sleep(1)
            if self.end_from_trigger: 1
                 self.log.info("Sensor time condition reached; marking task successful and exiting")
                 yield TaskSuccessEvent()
88
             else:
                 self.log.info("yielding event with payload %r", self.moment)
                 yield TriggerEvent(self.moment)
```



Yield a TaskSuccessEvent

```
if self.end_from_trigger::
    self.log.info("Sensor time condition reached; marking task successful and exiting"):
    yield TaskSuccessEvent():
    else::
        self.log.info("yielding event with payload %r", self.moment):
        yield TriggerEvent(self.moment):
```



Newly supported TriggerEvents

```
class TaskSuccessEvent(BaseTaskEndEvent):
                                                                             """Yield this event in order to end the task successfully."""

| Task | Successfully | Task | 
                                                                                  task_instance_state = TaskInstanceState.SUCCESS
                                              class TaskFailedEvent(BaseTaskEndEvent):
                                                                                   """Yield this event in order to end the task with failure."""1
10
                                                                                   task_instance_state = TaskInstanceState.FAILED
11
12
13
                                              class TaskSkippedEvent(BaseTaskEndEvent): 
                                                                                   """Yield this event in order to end the task with status 'skipped'."""

| Task | Status | Skipped | Skippe
14
15
16
                                                                                  task_instance_state = TaskInstanceState.SKIPPED
```



Under the hook

```
triggerer_job_runner.py
      class TriggererJobRunner(BaseJobRunner, LoggingMixin):
163
         @add_span 7
          def handle_events(self):
              """Dispatch outbound events to the Trigger model which pushes
              while self.trigger_runner.events:
               --- # Get the event and its trigger ID:
                  trigger_id, event = self.trigger_runner.events.popleft();
                  # Tell the model to wake up its tasks:
                  Trigger.submit_event(trigger_id=trigger_id, event=event)
                  # Emit stat event]
                  Stats.incr("triggers.succeeded")
```



Under the hook



Under the hook, it updates the state...

```
triggerer_job_runner.py x
                                      trigger.py
                                                             base.py
     class BaseTaskEndEvent(TriggerEvent):
33
         @provide_session
12
         def handle_submit(self, *, task_instance: TaskInstance, session: Session = NEW_SESSION) -> None: I
10
             Submit event for the given task instance.
             Marks the task with the state `task_instance_state` and optionally pushes xcom if applicable.
             :param task_instance: The task instance to be submitted.
             :param session: The session to be used for the database callback sink.↓
             # Mark the task with terminal state and prevent it from resuming on worker.
             task_instance.trigger_id = None
             task_instance.state = self.task_instance_state
200
             self._submit_callback_if_necessary(task_instance=task_instance, session=session)
             self._push_xcoms_if_necessary(task_instance=task_instance)
```



based on the TriggerEvent type

```
class TaskSuccessEvent(BaseTaskEndEvent): ]
                                                                             """Yield this event in order to end the task successfully."""

| Task | Successfully | Task | 
                                                                                 task_instance_state = TaskInstanceState.SUCCESS
                                              class TaskFailedEvent(BaseTaskEndEvent):
                                                                                   """Yield this event in order to end the task with failure."""1
10
                                                                                   task_instance_state = TaskInstanceState.FAILED
11
12
13
                                              class TaskSkippedEvent(BaseTaskEndEvent): 
                                                                                   """Yield this event in order to end the task with status 'skipped'."""

| Task | Status | Skipped | Skippe
14
15
16
                                                                                  task_instance_state = TaskInstanceState.SKIPPED
```



which used to be always set as SCHEDULED

```
1 9 airflow/models/trigger.py
              @@ -203,14 +203,7 @@ def submit_event(cls, trigger_id, event, session: Session = NEW_SESSION) -> None
       203
203
                              TaskInstance.trigger id == trigger id, TaskInstance.state == TaskInstanceState.DEFERRED
204
      204
                      ):
205
      205
206
                          # Add the event's payload into the kwargs for the task
                          next_kwargs = task_instance.next_kwargs or {}
207
                          next_kwarqs["event"] = event.payload
208
                          task instance.next kwargs = next kwargs
209
210
                          # Remove ourselves as its trigger
                          task_instance.trigger_id = None
211
212
                          # Finally, mark it as scheduled so it gets re-queued
212
                          task_instance.state = TaskInstanceState.SCHEDULED
                          event.handle submit(task instance=task instance)
       206
```





Credit

author of the end from trigger feature

Ankit Chaurasia



Senior Software Engineer at Astronomer

Ankit Chaurasia is a Senior Software Engineer at Astronomer, where he focuses on the design and engineering of Apache Airflow. He is an advocate for open-source projects and has contributed to initiatives such as Apache Airflow, Ask-Astro, and OpenCV CVAT. Previously, Ankit led teams at Wadhwani AI, developing AI solutions for healthcare and agriculture, which resulted in winning a \$2 million Google AI Challenge grant.

More at https://ankitchaurasia.info/

Sessions by Ankit Chaurasia

Mastering Advanced Dataset Scheduling in Apache Airflow (2024)

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17:40 at the same room

Mastering Advanced Dataset Scheduling in Apache Airflow

Speaker(s):



Ankit Chaurasia

Sep-11 17:40-18:05 in Elizabethan A+B



Are you looking to harness the full potential of data-driven pipelines with Apache Airflow? This session will dive into the newly introduced conditional expressions for advanced dataset scheduling in Airflow - a feature highly requested by the Airflow community. Attendees will learn how to effectively use logical operators to create complex dependencies that trigger DAGs based on the dataset updates in real-world scenarios. We'll also explore the innovative DatasetOrTimeSchedule, which combines time-based and dataset-triggered scheduling for unparalleled flexibility. Furthermore, attendees will discover the latest API endpoints that facilitate external updates and resets of dataset events, streamlining workflow management across different deployments.

This talk also aims to explain:

- The basics of using conditional expressions for dataset scheduling.
- How do we integrate time-based schedules with dataset triggers?
- Practical applications of the new API endpoints for enhanced dataset management.
- Real-world examples of how these features can optimize your data workflows.



How does it affect DAG authors?

- Release more worker slot
- Improve operators and sensors for efficiency
- Reduce resource usage, which indicates cost saving
- More new use cases to come after more operator authors apply this new feature



How does it affect operator authors?

- A new way to implement operators in an asynchronous manner
- Simplify operators / sensors by reducing unnecessary "execute" and "execute_complete" methods (most applicable to sensors I think)



How does it affect Airflow?

Potential to run all tasks in async



How does it affect Airflow?

Potential to run all tasks in async?



They're included in Airflow 2.10.0 🎉



You can find it if you scroll down to the end of Airflow 2.10.0 post

Additional new features

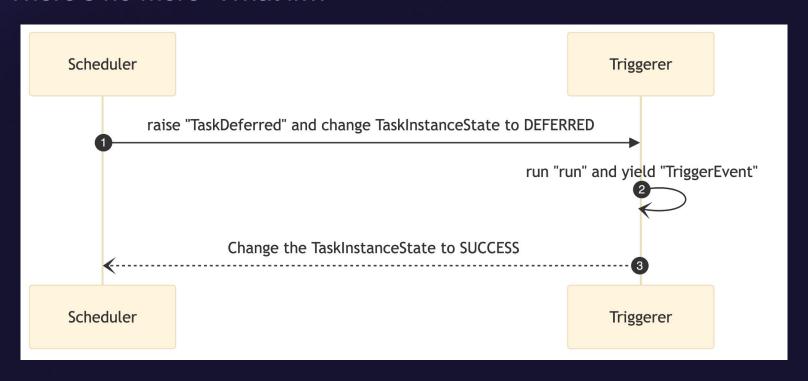
Here are just a few interesting new features since there are too many to list in full:

 Deferrable operators can now execute directly from the triggerer without needing to go through the worker. This is especially efficient for certain operators, like sensors, and can help teams save both time and money.



Running Airflow Tasks without the workers

There's no more "What if..."

















Limited dynamic task mapping support

```
class WaitHoursSensor(BaseSensorOperator):
        # You'll need to change trigger_cls to the actual path to HourDeltaTrigger.
    timeout=None,
    . . . . ) ]
    def __init__(
    self,
    *args: list[Any],
    trigger_kwargs: dict[str, Any] | None,
    start_from_trigger: bool,
    **kwargs: dict[str, Any],
    ) -> None: 1
           # This whole method will be skipped during dynamic task mapping.
26
           super().__init__(*args, **kwargs)
           self.start_trigger_args.trigger_kwargs = trigger_kwargs
           self.start_from_trigger = start_from_trigger
```



trigger_kwargs, start_from_trigger required in __init__

```
class WaitHoursSensor(BaseSensorOperator):
        # You'll need to change trigger_cls to the actual path to HourDeltaTrigger.
    timeout=None,
    · · · · ) ]
    def __init__(
    self, ↓
    *oras. list[Anv]
    trigger_kwargs: dict[str, Any] |
    start_from_trigger: bool, \( \)
         **kwargs: alctLstr, Any],
    ) -> None: \
            # This whole method will be skipped during dynamic task mapping.
26
           super().__init__(*args, **kwargs);
            self.start_trigger_args.trigger_kwargs = trigger_kwargs
            self.start_from_trigger = start_from_trigger
```



the whole __init__ method skipped before execution

```
class WaitHoursSensor(BaseSensorOperator):
         # You'll need to change trigger_cls to the actual path to HourDeltaTrigger.
             timeout=None, 1
10
    . . . . ) フ
             # This whole method will be skipped during dynamic task mapping.
```



slightly different syntax

```
WaitHoursSensor.partial(
   task_id="wait_for_n_hours", \1
start_from_trigger=True
).expand(]
➡ trigger_kwargs=[コ
{"hours": 1},
{"hours": 2}
```



If you don't know if you need to combine this feature with dynamic task mapping





Doesn't support listeners



Exiting from the trigger works only when listeners are not integrated for the deferrable operator. Currently, when deferrable operator has the end_from_trigger attribute set to True and listeners are integrated it raises an exception during parsing to indicate this limitation. While writing the custom trigger, ensure that the trigger is not set to end the task instance directly if the listeners are added from plugins. If the end_from_trigger attribute is changed to different attribute by author of trigger, the DAG parsing would not raise any exception and the listeners dependent on this task would not work. This limitation will be addressed in future releases.



QR Code links to my posts related to this talk





Thank you! Any questions?